



# Gaia: Global AI Accelerator: Modeling MJO structures and tipping point analysis

## **Milestone 6**

Preliminary software for the hybrid models/methods

## **Date of Report:**

Initially submitted Jul 13, 2022

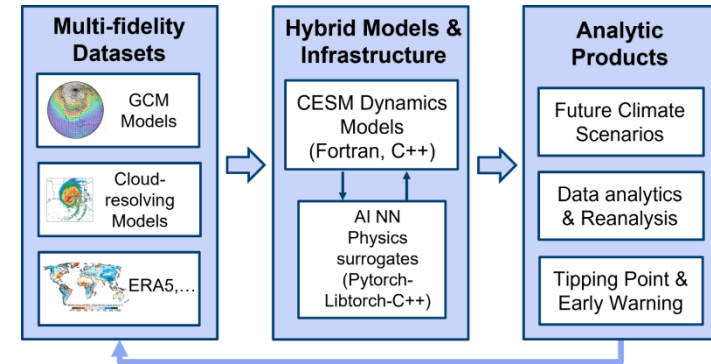
Updated: Aug 13, 2022

# Gaia: Global AI Accelerator



## Goals:

- Improve speed & skill of atmospheric models using hybrid AI cloud physics surrogates:
  - Accurately model local convection
  - Predict self-organizing atmospheric phenomena, e.g. MJO
- Exploit hybrid models to explore future climate regimes and identify early tipping point signatures



## Why is this Hard?

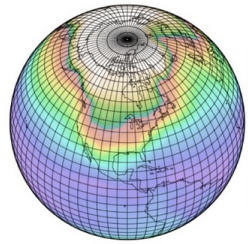
- Global climate models (GCMs) are computationally expensive and lack the resolution required to model local convection and clouds
- This restricts our ability to model convection processes including wave phenomena such as MJO, and limits forecasting skill and the ability to explore future climate regimes

## Key Gaia ideas and approach:

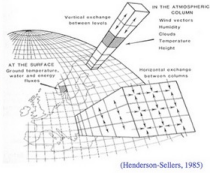
- Use AI surrogates to model cloud physics to substantially increase computational efficiency
- Use LES and reanalysis data to learn corrections to the AI surrogate models with the goal of improved MJO modeling while retaining computational efficiency
- Use improved hybrid models and reduced order models to explore tipping point regimes (such as predicted “superMJO”) and early warning signatures

# Gaia Hybrid Model Building Approach

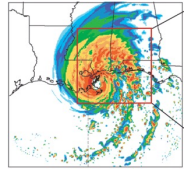
## Datasets for AI Training



CGM-CAM4

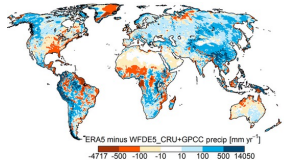


CGM-SPCAM



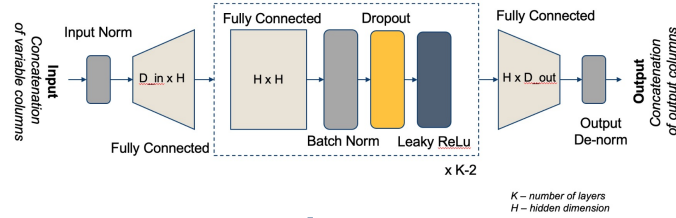
WRF-LES

Cloud-resolving Models



Reanalysis Datasets  
(e.g. ERA5)

## AI NN Surrogate Cloud Physics Model(s) (e.g. FC, CNN, AE, Resnet)



AI CAM-trained  
NN Surrogate Model(s)

AI NN  
Corrective Model(s)

+

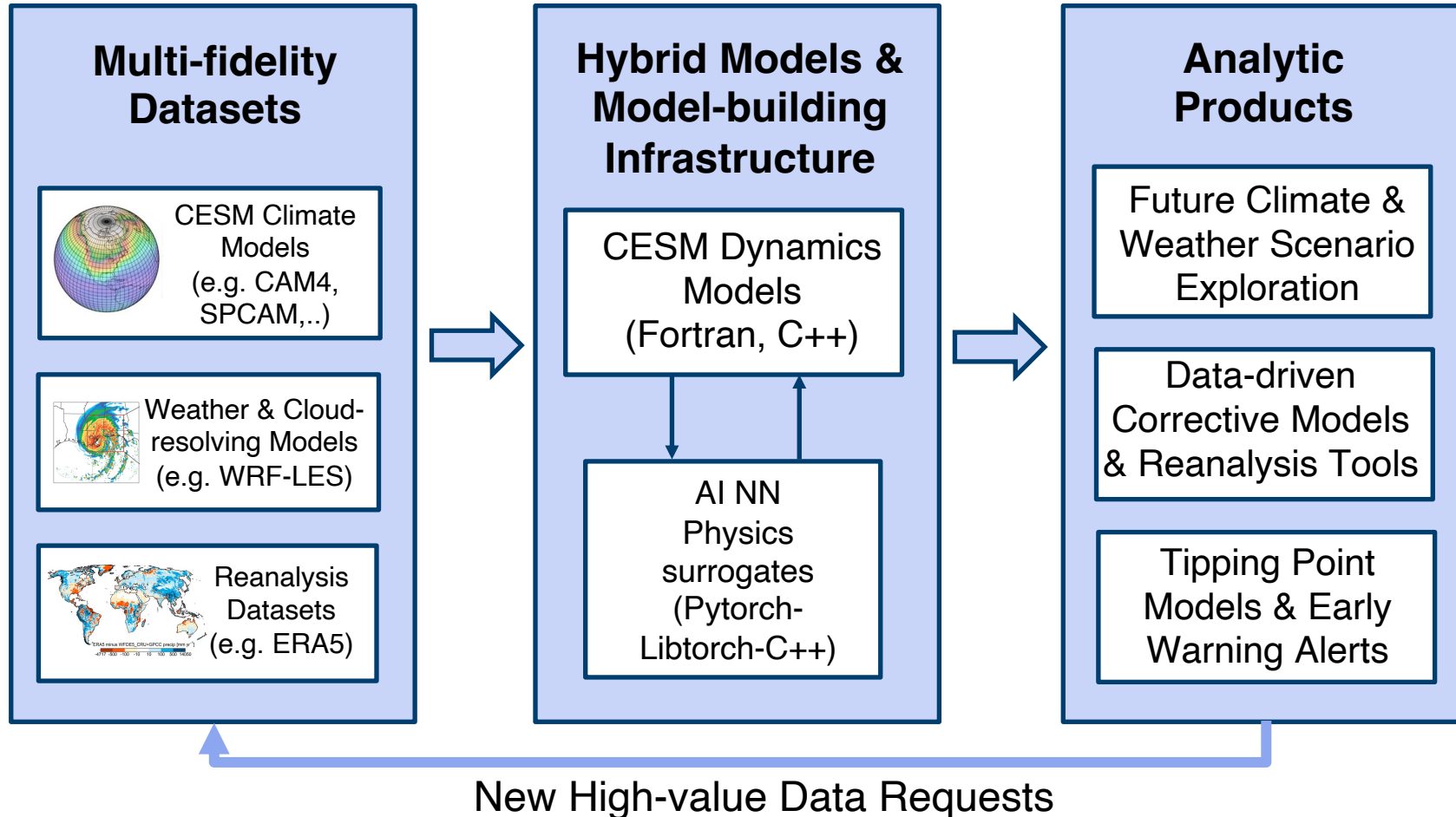
## Hybrid Model(s)

GCM Dynamics  
(Fortran, C++)

AI NN  
Cloud Physics  
(Pytorch-  
Libtorch-C++)

Predicted  
Trajectory

# Gaia Building Blocks & Products



# M6 Update



Description of datasets, data preprocessing, python modeling & analytics, and data products can be found at:

<https://github.com/stresearch/gaia>

Training of initial AI cloud physics model surrogates is currently based on 3 and 4-year runs from two NCAR community atmospheric models (CAM4 and SPCAM); these datasets have been reproduced with *additional variables*\* identified as useful for the hybrid model, and will later be extended to 10 years of simulation time:

## GCM

- [Community Atmospheric Model \(CAM4\)](#)
- 30 minute time-step
- 2.5-degree grid (144x96)
- 30 altitude levels
- Four year run (1979 SST; Time Varying) which will be extended to ten years.
- Outputs every 3 hours + additional model time-step (memory)

## CRM

- [SPCAM \(super parameterized CAM\)](#)
- 20 minute time-step
- 16 SAM (The System for Atmospheric Modeling) Columns
- 26 levels
- Year 2000 SST (Climatology)
- Three year simulations:
  - Morrison Microphysics + Conventional parameterization for moist convection and large-scale condensation.
  - Morrison Microphysics + Higher-order turbulence closure scheme, Cloud Layers Unified By Binormals (CLUBB)
- Outputs every 3 hours + additional model time-step (memory)

\* See following slides

# Gaia AI inputs (state info passed from GCM)



## Surrogate Inputs

| Name         | Long Name                             | shape               | unit        |
|--------------|---------------------------------------|---------------------|-------------|
| Q            | Specific humidity                     | (T, L, 96, 144)     | kg/kg       |
| T            | Temperature                           | (T, L, 96, 144)     | K           |
| U            | Zonal wind                            | (T, L, 96, 144)     | m/s         |
| V            | Meridional wind                       | (T, L, 96, 144)     | m/s         |
| OMEGA        | Vertical velocity (pressure)          | (T, L, 96, 144)     | Pa/s        |
| Z3           | Geopotential Height (above sea level) | (T, L, 96, 144)     | m           |
| PS           | Surface pressure                      | (T, 96, 144)        | Pa          |
| <b>SOLIN</b> | <b>Solar insolation</b>               | <b>(T, 96, 144)</b> | <b>W/m2</b> |
| SHFLX        | Surface sensible heat flux            | (T, 96, 144)        | W/m2        |
| LHFLX        | Surface latent heat flux              | (T, 96, 144)        | W/m2        |
| FSNS         | Net solar flux at surface             | (T, 96, 144)        | W/m2        |
| FLNS         | Net longwave flux at surface          | (T, 96, 144)        | W/m2        |
| FSNT         | Net solar flux at top of model        | (T, 96, 144)        | W/m2        |
| FLNT         | Net longwave flux at top of model     | (T, 96, 144)        | W/m2        |
| FSDS         | Downwelling solar flux at surface     | (T, 96, 144)        | W/m2        |

\* Note that at this stage we are not adding 4D radiative inputs (e.g. SOLL)

# Gaia AI outputs (state info passed to GCM)



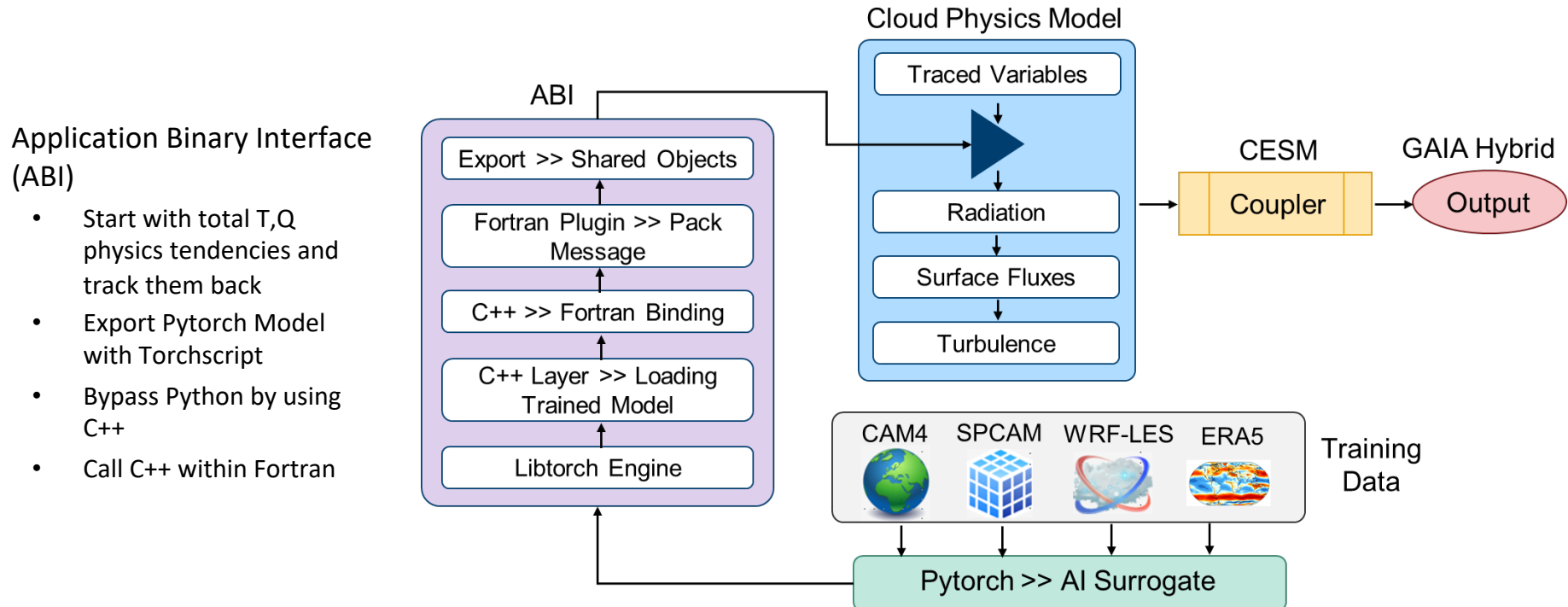
## Surrogate Outputs

| Name          | Long Name  | shape               | unit       |
|---------------|--|---------------------|------------|
| PTEQ          | Q total physics tendency                           | (T, L, 96, 144)     | kg/kg/s    |
| PTTEND        | T total physics tendency                           | (T, L, 96, 144)     | k/s        |
| DCQ           | Q total tendency moist processes                   | (T, L, 96, 144)     | kg/kg/s    |
| DTCOND        | T total tendency moist processes                   | (T, L, 96, 144)     | k/s        |
| QRS           | Shortwave heating rate                             | (T, L, 96, 144)     | k/s        |
| QRL           | Longwave heating rate                              | (T, L, 96, 144)     | k/s        |
| CLOUD         | Total cloud cover                                  | (T, L, 96, 144)     | fraction   |
| CONCLD        | Convective cloud cover                             | (T, L, 96, 144)     | fraction   |
| FSNS          | Net solar flux at surface                          | (T, 96, 144)        | W/m2       |
| FLNS          | Net longwave flux at surface                       | (T, 96, 144)        | W/m2       |
| FSNT          | Net solar flux at top of model                     | (T, 96, 144)        | W/m2       |
| FLNT          | Net longwave flux at top of model                  | (T, 96, 144)        | W/m2       |
| FSDS          | Downwelling solar flux at surface                  | (T, 96, 144)        | W/m2       |
| FLDS          | Downwelling longwave flux at surface               | (T, 96, 144)        | W/m2       |
| SRFRAD        | Net radiative flux at surface                      | (T, 96, 144)        | W/m2       |
| SOLL          | Solar downward near infrared direct to surface     | (T, 96, 144)        | W/m2       |
| SOLS          | Solar downward visible direct to surface           | (T, 96, 144)        | W/m2       |
| SOLLD         | Solar downward near infrared diffuse to surface    | (T, 96, 144)        | W/m2       |
| SOLSD         | Solar downward visible diffuse to surface          | (T, 96, 144)        | W/m2       |
| PSL           | Sea level pressure                                 | (T, 96, 144)        | W/m2       |
| <b>PRECT</b>  | <b>Total precipitation rate (liquid+ice)</b>       | <b>(T, 96, 144)</b> | <b>m/s</b> |
| <b>PRECC</b>  | <b>Convective precipitation rate (liquid+ice)</b>  | <b>(T, 96, 144)</b> | <b>m/s</b> |
| <b>PRECL</b>  | <b>Large-scale precipitation rate (liquid+ice)</b> | <b>(T, 96, 144)</b> | <b>m/s</b> |
| <b>PRECSC</b> | <b>Convective snow rate</b>                        | <b>(T, 96, 144)</b> | <b>m/s</b> |
| <b>PRECSL</b> | <b>Large-scale snow rate</b>                       | <b>(T, 96, 144)</b> | <b>m/s</b> |

# Hybrid model integration



- Completed integrating the pytorch-based AI surrogate back into the Fortran-based GCM models
- Both the traditional parameterized physics model and the AI/ML surrogate physics model integrations can run side by side in the same run for comparison
- Currently debugging binding problem in the C++-Fortran binding code





# Code components



|                                   |
|-----------------------------------|
| initindx.F90                      |
| machine_learning_model.F90        |
| machine_learning_model_config.F90 |
| ml_solin.F90                      |
| ml_srfxfer.F90                    |
| physpkg.F90                       |
| tphysac.F90                       |
| tphysac_param.F90                 |
| tphysbc.F90                       |
| tphysbc_ml.F90                    |
| tphysbc_param.F90                 |

|                     |
|---------------------|
| CMakeLists.txt      |
| torch-plugin.f90    |
| torch-wrap-cdef.f90 |
| torch-wrap.cpp      |

- \*.config.F90 file provides configurations to switch on/off different physical processes (e.g. radiation)
- \*solin.F90 takes out solar insolation calculations out of radiation (makes easy to bypass complex radiative calculations)
- tphysac\* and tphysbc\* provide the gateway for the ABI to function
- Machine\_learning\_model.F90 reads in data from the ABI
- ABI Wrappers
  - Torch-wrap\* contains wrappers and definitions for the Libtorch and C++ binding to function
  - \*plugin loads the Pytorch model into the CESM code base

# Hybrid model characteristics



Architected as a set of modular building blocks for easy adoption and easy extension by the community

## Flexibility

- Switches enabled to run hybrid & parameterized physics in a single time step.

## Generalizability

- Extendable to replace other physics parameterizations such as radiation, boundary layer and surface schemes due to modular code structure.

## Modularity & Reliability

- Implementation fits nicely with CESM and can be joined with the CESM source tree efficiently.

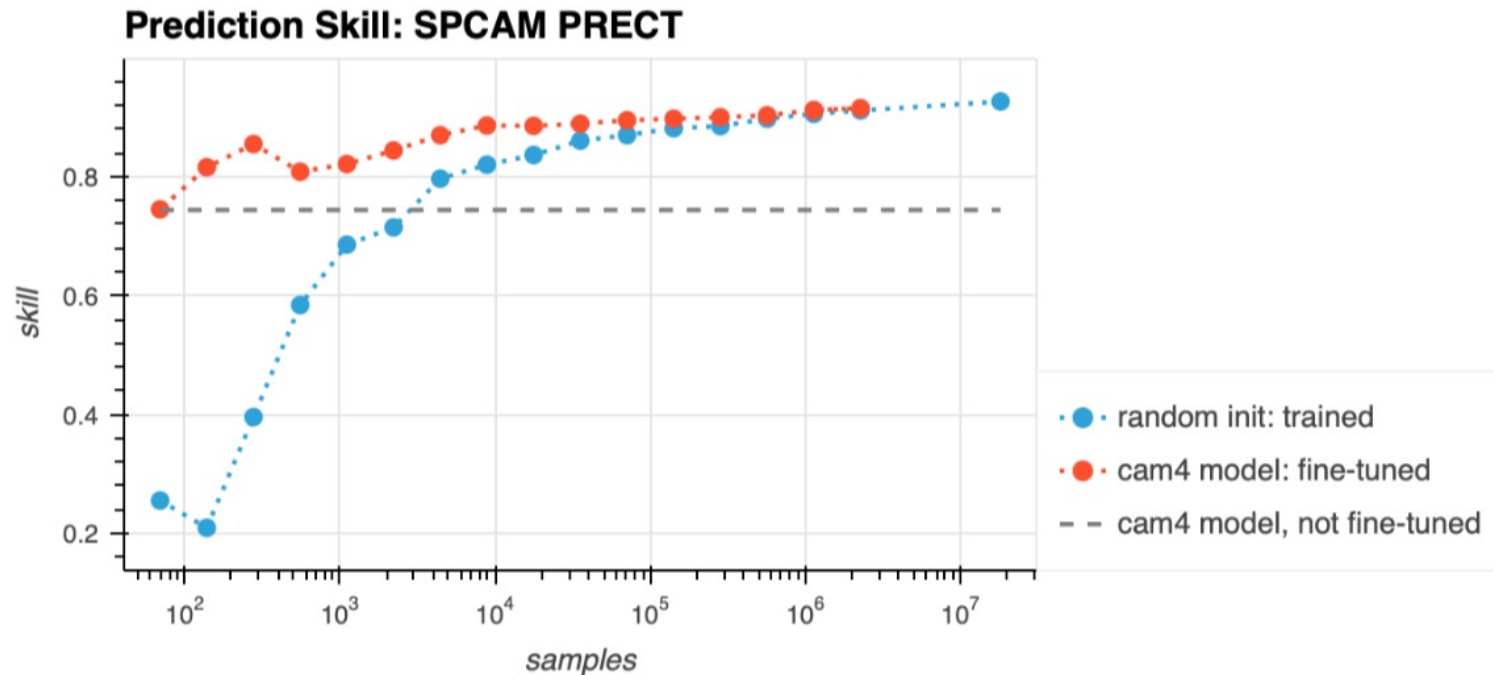
## Performance

- Faster to run by > 3X than initial parameterized runs depending on the complexity of the ML trained model.

# Exploring fine-tuning a model for a subset of output variables



- Fine-tune CAM4-trained model to predict SPCAM total precipitation
- Compare to SPCAM-trained model trained from scratch
- SPCAM testset used, looking at total precipitation output variable only
- Prediction skill reaches ~92%, (CAM4-trained model on CAM4 testset reaches 96% skill)



# Gaia Current Status (Aug 13, 2022)



## Completed

- Initial CAM4 and SPCAM datasets generated (4 years, 30/20 min timestep)
- Developed & optimized several AI surrogates for both CAM4 and SPCAM
  - Validated AI skill for several architectures (FC, CNN, bottlenecked FC, transformer)
  - Dimensional analysis to quantify model complexity; also assessed impact of memory terms
  - Jacobian analyses as potential new skill metric and means of regularization
- Hybrid model machinery developed
  - Integrates pytorch AI surrogates into NCAR's Fortran GCM models
  - ~ 3X speedups
  - New CAM4 and SPCCAM datasets generated to accommodate additional variables

## Ongoing

- Run hybrid models and evaluate for stability, skill, and MJO modeling

## Next Steps

- Stability enforcing methods (if needed)
- AI retraining and augmentation (using WRF/LES model data and ERA5 reanalysis data)
- Explore forcings (e.g. high SST state regimes)
- Reduced order tipping point model development

# Hybrid model stability



Stability of deep neural net surrogates coupled into global atmospheric climate models has been an issue reported in the literature, e.g.:

- N. D. Brenowitz, T. Beucler, M. Pritchard, C. S. Bretherton, “Interpreting and Stabilizing Machine Learning Parameterizations of Convection”, J. Atmos. Sci., 2020
- X. Wang, Y. Han, W. Xue, G. Yang, G. J. Zhang, “Stable climate simulations using a realistic general circulation model with neural network parameterizations for atmospheric moist physics and radiation processes”, GeoSci. Model. Dev., 2022
- Problems manifest as rapid blowup in time of the total energy of the system; this can happen even for high-skill DNN surrogates
- Problem is not fully understood
- Solutions are mostly heuristic, and include:
  - Alternative network architectures, e.g. ResNets
  - Input variable ablation
  - Denoising architectures
  - Optimizing for wave propagation response in a linearized model
- Problem raises the concern that retrained AI’s (e.g. using LES or ERA datasets) might also exhibit stability issues when integrated back into GCM



# Approaches to hybrid model stability

We are just beginning to test the hybrid models; first steps will be to:

- Quantify hybrid model stability
- Quantify hybrid model skill on mean properties
- Quantify hybrid model skill in reproducing MJO-type structures
- Compare SPCAM and CAM4 hybrid models

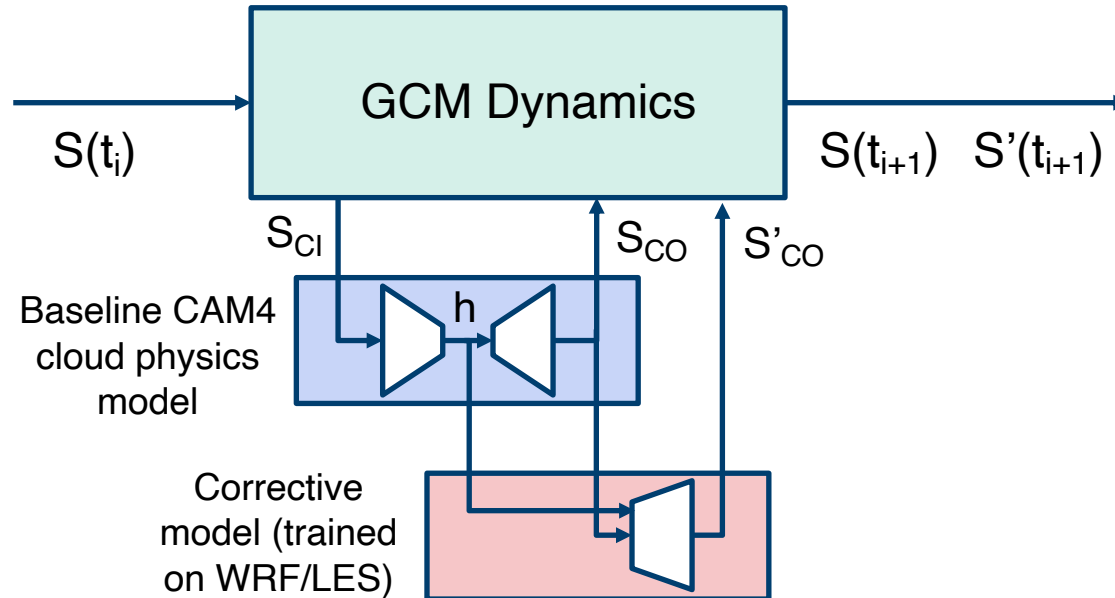
We are considering several approaches to address potential stability problems of the coupled AI-GCM hybrid models:

- First assess if problem is triggered by amplified skill errors, out-of-training behavior, non-causal AI behaviors, or other
- Assess local Jacobian of DNN input-to-output map in trouble areas, identify common features and potential spectral regularization methods
- Assess if problems are agnostic to AI architecture and/or AI model skill
- Assess impact of added memory terms or other approaches to encouraging causality
- Assess dimensional reduction regularization methods to improve generalizability
- Assess if AI surrogates conditioned on latitude and/or season perform more reliably
- Assess impact of data augmentation near trouble zones
- Assess impact of alternative normalizations

# Another idea for hybrid model(s) training



Consider a 2-step process: (1) train CAM physics model surrogate as before; (2) train corrections to this baseline model based on performance of hybrid model



Training of corrective model based on cost function looking at various skill metrics, stability, and  $S'$  residuals

# Another approach to gray-box corrections



- Constrain the NN **to possess the desired coarse bifurcation diagram**
- The coarse steady states as well as their coarse stabilities
- Prescribe this as part of the loss ---
  - OPTIMIZING NNs with algebraic constraints (KKT optimization)
- Separately **LIFTING in multiscale problems:**
  - **construct full model IC consistent with given coarse features:**
  - Initializing on slow manifolds / Umbrella Sampling / GANs
  - Coarse: e.g. Majda skeletal Madden-Julian States; Fine: current models



# CFD Example: data-driven corrective models from simulation data



Goal: Hardwire partially known physics in the structure of the ML algorithm (e.g. ANN) that learns the PDE from data

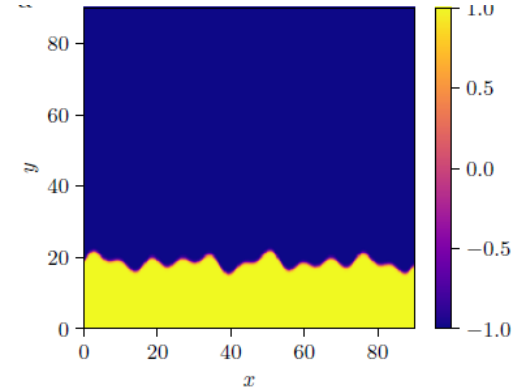
(a) as an additive correction to a known, approximate equation

(b) as a functional correction

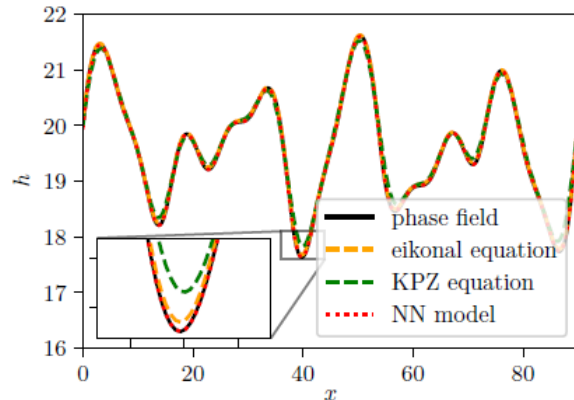
$$\frac{\partial \phi}{\partial t} = D \nabla^2 \phi - (\phi - a)(\phi^2 - 1)$$

An illustrative example: a phase field equation, with 2D vector field  $\phi$  and 1D boundary  $h$  for which two levels of approximate interface equations can be derived:

Eikonal 
$$\frac{\partial h}{\partial t} = \frac{D}{1 + \left(\frac{\partial h}{\partial x}\right)^2} \frac{\partial^2 h}{\partial x^2} - \sqrt{2Da} \sqrt{1 + \frac{1}{2} \left(\frac{\partial h}{\partial x}\right)^2}$$
 and KPZ 
$$\frac{\partial \tilde{h}}{\partial t} = D \frac{\partial^2 \tilde{h}}{\partial x^2} - a \sqrt{\frac{D}{2}} \left(\frac{\partial \tilde{h}}{\partial x}\right)^2$$



Black box NN model performance:



Additive Correction to KPZ

$$\begin{aligned} \widehat{\frac{\partial h}{\partial t}} &= f_{KPZ}(h, \partial h / \partial x, \partial^2 h / \partial x^2) \\ &+ NN_{\Theta}(h, \partial h / \partial x, \partial^2 h / \partial x^2) \\ &= f_{add}(h, \partial h / \partial x, \partial^2 h / \partial x^2). \end{aligned}$$

Functional Correction to KPZ

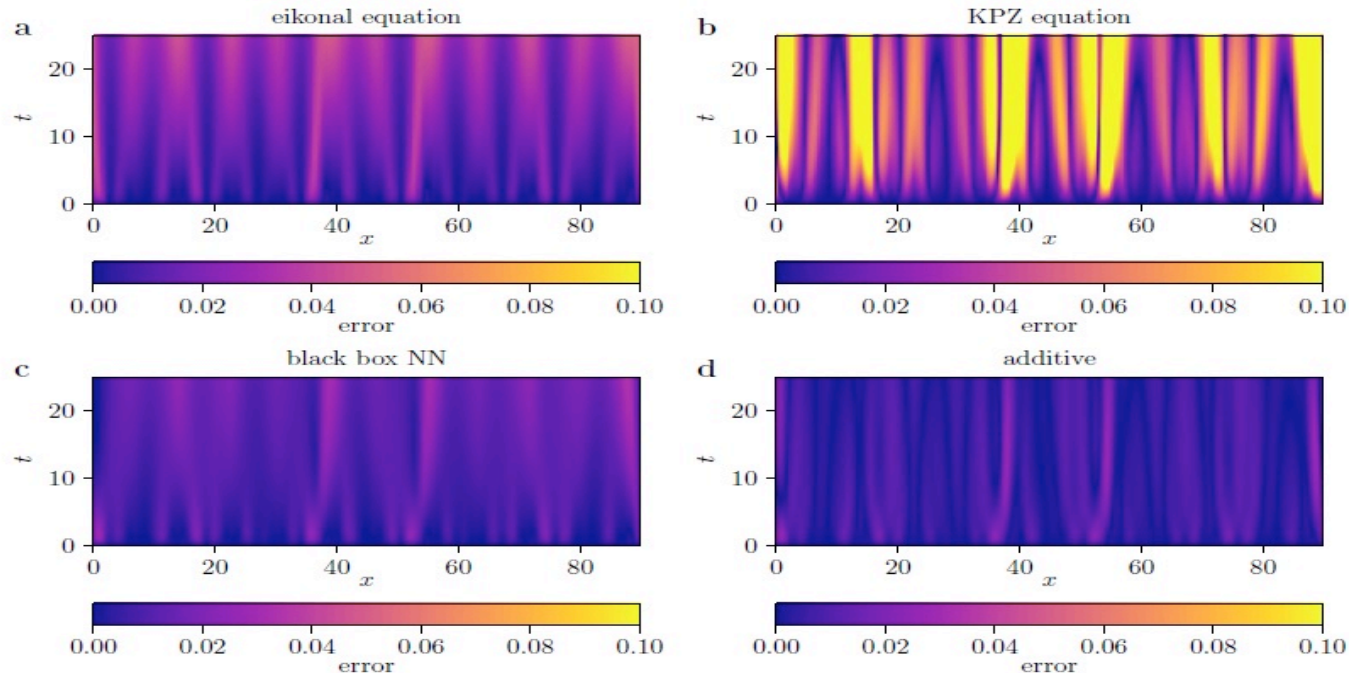
$$\begin{aligned} \widehat{\frac{\partial h}{\partial t}} &= NN_{\Theta}(f_{KPZ}, \partial f_{KPZ} / \partial x, \partial^2 f_{KPZ} / \partial x^2) \\ &= f_{fun}(f_{KPZ}, \partial f_{KPZ} / \partial x, \partial^2 f_{KPZ} / \partial x^2). \end{aligned}$$

# Comparison of space-time errors for Eikonal, KPZ, black box NN, and corrective NN



Note: while black box NN provides a better mapping than either Eikonal or KPZ approximations, learning a NN correction to the KPZ approximation does better yet!

We plan to exploit this corrective gray box approach to improve our AI surrogate model performance

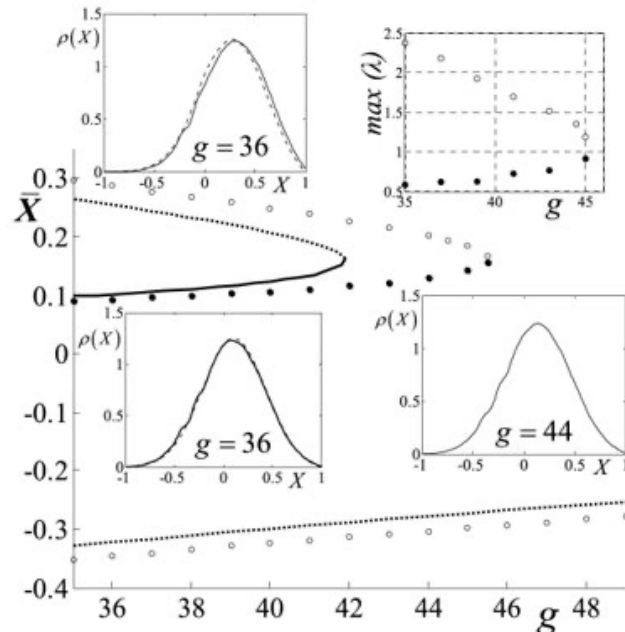


# On tipping point analysis with reduced-dimension models

Goal: build targeted bifurcation surrogates close to tipping points

Example: complex economic stochastic agent-based model with 50,000 agents

Type of tipping point: fold (turning point)



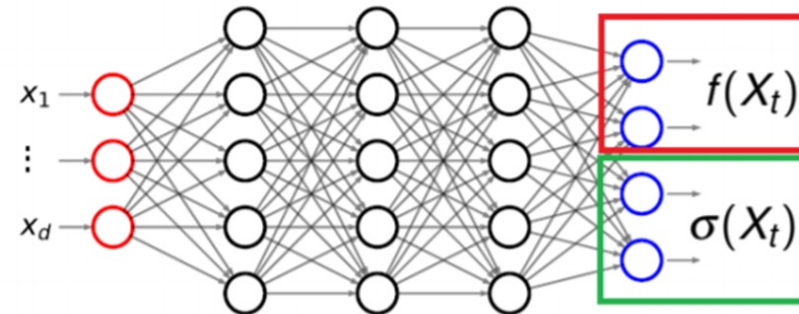
Agent distribution mean depends on parameter  $g$ , with tipping point at  $g \sim 45$

To learn an SDE

$$dX_t = f(X_t)dt + \sigma(X_t)dW_t$$

We need to approximate the drift and diffusivity.

Using a Deep Neural Network.

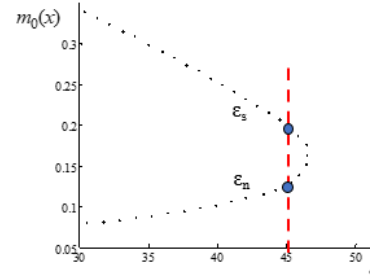
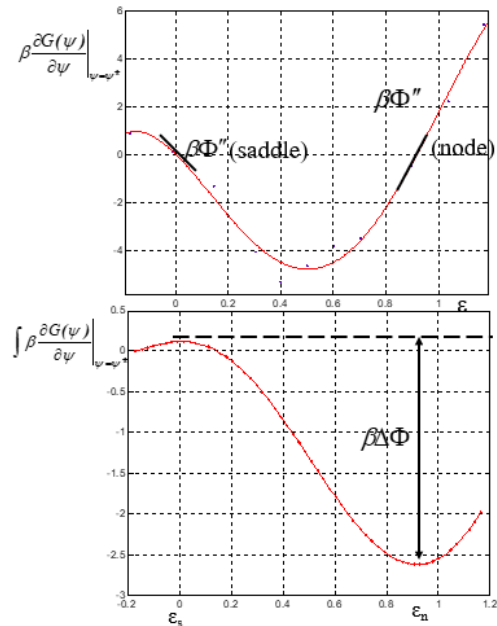


Use DNN to learn stochastic differential equation representation of behavior close to tipping point

# Tipping point modeling, cont.

Kramer's theory for modeling Brownian escape times

System properties are obtained from short-scale nonequilibrium simulations (at  $g = 45.2$  in this example) and the learned stochastic differential equation



$$\frac{\partial \psi(t; \psi_0)}{\partial t} \approx -D \beta \frac{\partial G(\psi)}{\partial \psi} \Big|_{\psi=\psi^*}$$

$$\frac{d \text{var}[\psi(t; \psi_0)]}{dt} \approx 2D(\psi^*)$$

mean time to escape

$$\tau \approx \frac{2\pi}{D \sqrt{\beta \Phi''(N_{min}) \beta \Phi''(N_{saddle})}} e^{\beta \Delta \Phi}$$

Key idea: for many complex systems, the tipping point dynamics becomes low (even 1D) dimensional close to a tipping point; we will attempt to learn a reduced dimensional tipping point model from our hybrid model at strong forcing (e.g., for elevated sea surface temperatures)

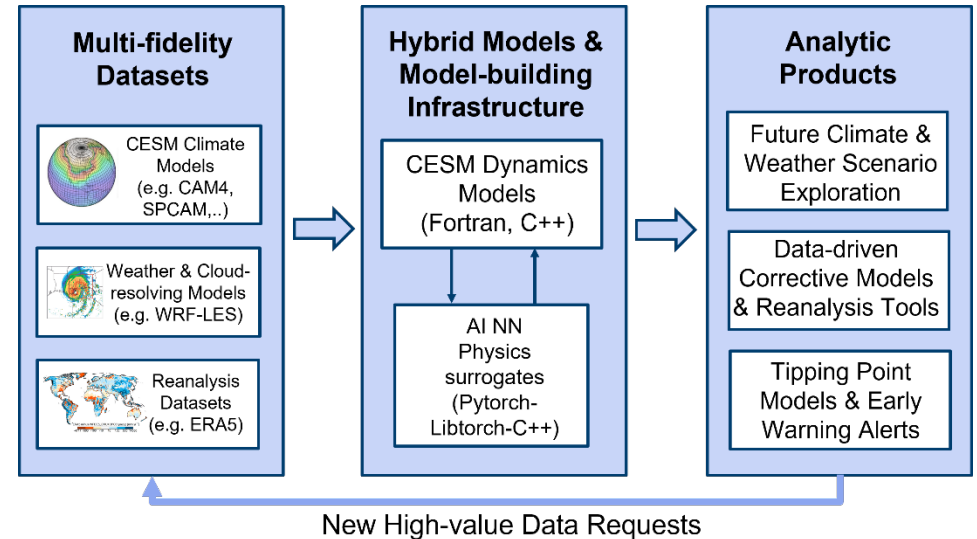
# Summary

## Completed

- Generated several training datasets
- Trained and validated an ensemble of AI surrogates
- Completed large engineering task of hybrid model infrastructure build

## Next Phase I Steps

- Evaluate hybrid models
- Test new approaches to guarantee model stability and skill
- Test new approaches to build in model corrections using high fidelity model and observational data
- Develop reduced dimensional models, regularization on skeletal models, tipping point models



## Phase 2 Analytic Products

- Fast “what if” trajectory analysis under forcing conditions
- Early warning tipping point signatures
- Data-driven model corrections
- Quantify value of new data